

# A Review: Remote Sensing Sensors

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**Abstract:** The cost of launching satellites is getting lower and lower due to the reusability of rockets (NASA, 2015) and using single missions to launch multiple satellites (up to 37, Russia, 2014). In addition, low-orbit satellite constellations have been employed in recent years. These trends indicate that satellite remote sensing has a promising future in acquiring high-resolution data with a low cost and in integrating high-resolution satellite imagery with ground-based sensor data for new applications. These facts have motivated us to develop a comprehensive survey of remote sensing sensor development, including the characteristics of sensors with respect to electromagnetic spectrums, imaging and non-imaging sensors, potential research areas, current practices, and the future development of remote sensors.

**Keywords:** Remote sensing, satellite, sensors, electromagnetic spectrum, spectrum of materials, imaging sensors, non-imaging sensors

## 1. Introduction

In 2015, one of the most remarkable events in the space industry was when SpaceX realized the reusability of its rocket for the first time. Additionally, in June of 2014, Russia used one rocket to launch 37 satellites at the same time. At present, many countries have the capability to launch multiple satellites in one mission. For example, NASA and the US Air Force launched 29 satellites in a single mission in 2013. At that time, the mission represented the most satellites ever launched at one time [1]. In 2015 and 2016, China and India launched 20 satellites in single mission, respectively. At present, six organizations have the capability to launch multiple satellites in a single mission: Russia, USA, China, India, Japan, and ESA. This

trend indicates that in the future, the cost in sending satellites to space will greatly decrease. More and more remote sensing resources are becoming available. It is of great importance to have a comprehensive survey of the available remote sensing technology and to utilize inter- or trans-disciplinary knowledge and technology to create new applications.

Remote sensing is considered a primary means of acquiring spatial data. Remote sensing measures electromagnetic radiation that interacts with the atmosphere and objects. Interactions of electromagnetic radiation with the surface of the Earth can provide information not only on the distance between the sensor and the object but also on the direction, intensity, wavelength, and polarization of the electromagnetic radiation [2]. These measurements can offer positional information about the objects and clues as to the characteristics of the surface materials.

Satellite remote sensing consists of one or multiple remote sensing instruments located on a satellite or satellite constellation collecting information about an object or phenomenon on the Earth surface without being in direct physical contact with the object or phenomenon. Compared to airborne and terrestrial platforms, spaceborne platforms are the most stable carrier. Satellites can be classified by their orbital geometry and timing. Three types of orbits are typically used in remote sensing satellites, including geostationary, equatorial and sun-synchronous orbits. A geostationary satellite has a period of rotation equal to that of Earth (24 hours) so the satellite always stays over the same location on Earth. Communications and weather satellites often use geostationary orbits with many of them located over the equator. In an equatorial orbit, a satellite circles the Earth at a low inclination (the angle between the orbital plane and the equatorial plane). The Space Shuttle uses an equatorial orbit with an inclination of 57 degrees. Sun-synchronous satellites have orbits with high inclination angles, passing nearly over the poles. Orbits are timed so that the satellite always passes over the equator at the same local sun time. In this way, these satellites maintain the same relative position with the sun for all of its orbits. Many remote sensing satellites are sun synchronous, which ensures repeatable sun illumination conditions during specific seasons. Because a sun-synchronous orbit does not pass directly over the poles, it is not always possible to acquire data for the extreme polar regions. The frequency at which a satellite sensor can acquire data for the entire Earth depends on the sensor and orbital characteristics [3]. For most remote sensing satellites, the total coverage frequency ranges from twice a day to once every 16 days. Another orbital characteristic is altitude. The space shuttle has a low orbital altitude of 300 km, whereas other common remote sensing satellites typically maintain higher orbits ranging from 600 to 1000 km.

The interaction between a sensor and the surface of the Earth has two modes: active or passive. Passive sensors utilize solar radiation to illuminate the Earth's surface and detect the reflection from the surface. Passive sensors typically record electromagnetic waves in the range of visible (~430–720 nm) and near-infrared (~750–950 nm) light. Some systems, such as SPOT 5, are also designed to acquire images in middle-infrared wavelengths (1,580–1,750 nm). The power measured by passive sensors is a function of the surface composition, physical temperature, surface roughness, and other physical characteristics of the Earth [4].

1 Examples of passive satellite sensors are those aboard the Landsat, SPOT, Pléiades, EROS,  
2 GeoEye and WorldView satellites. Active sensors provide their own source of energy to  
3 illuminate the objects and measure the observations. These sensors use electromagnetic waves  
4 in the range of visible light and near infrared (e.g., a laser rangefinder or a laser altimeter) and  
5 radar waves (e.g., synthetic aperture radar (SAR)). A laser rangefinder uses a laser beam to  
6 determine the distance between the sensor and the object and is typically used in airborne  
7 and ground-based laser scanning. A laser altimeter uses a laser beam to determine the altitude  
8 of an object above a fixed level and is typically utilized in satellite and aerial platforms. SAR  
9 uses microwaves to illuminate a ground target with a side-looking geometry and measures  
10 the backscatter and travel time of the transmitted waves reflected by objects on the ground.  
11 The distance that the SAR device travels over a target in the time taken for the radar pulses to  
12 return to the antenna produces the SAR image. SAR can be mounted on a moving platform,  
13 such as spaceborne and airborne platforms. According to the combination of frequency bands  
14 and polarization modes used in data acquisition, sensors can be categorized as single  
15 frequency (L-band, or C-band, or X-band), multiple frequency (a combination of two or more  
16 frequency bands), single polarization (VV, or HH, or HV), and multiple polarization (a  
17 combination of two or more polarization modes). Currently, there are three commercial SAR  
18 missions in space: Germany's TerraSAR-X and TanDEM-X (X-band with a ~3.5 cm  
19 wavelength), Italy's COSMO-SkyMed (X-band with ~3.5 cm wavelength) and Canada's  
20 RADARSAT-2 (C-band with ~6 cm wavelength). In addition, ESA's ERS-1, ERS-2 and Envisat  
21 also carried SAR, although these missions have ended. The latest SAR satellites from ESA  
22 include Sentinel-1A, Sentinel-1B, and Sentinel-3A. Typical SAR parameters are repeat  
23 frequency, pulse repetition frequency, bandwidth, polarization, incidence angle, imaging  
24 mode and orbit direction [5].

25 As sensor technology has advanced, the integration of passive and active sensors into one  
26 system has emerged. This trend makes it unclear difficult to categorize sensors in the  
27 traditional way, into passive sensors and active sensors. In this paper, we introduce the  
28 sensors in terms of imaging or non-imaging functionality. Imaging sensors typically employ  
29 optical imaging systems, thermal imaging systems or SAR. Optical imaging systems use the  
30 visible, near-infrared, and shortwave infrared spectrums and typically produce  
31 panchromatic, multispectral and hyperspectral imagery. Thermal imaging systems employ  
32 mid to longwave infrared wavelengths. Non-imaging sensors include microwave  
33 radiometers, microwave altimeters, magnetic sensors, gravimeters, Fourier spectrometers,  
34 laser rangefinders, and laser altimeters [6].

35 It has been decades since Landsat-1, the first Earth resources technology satellite, was  
36 launched in 1972. Satellite platforms have evolved from a single satellite to multi-satellite  
37 constellations. Sensors have experienced unprecedented development over the years, from  
38 1972 with the first multispectral satellite, Landsat-1, with four spectral bands to 1997 with the  
39 first hyperspectral satellite, Lewis, with 384 spectral bands. Spatial resolution has also  
40 significantly improved over the decades, from 80 m in Landsat-1 to 31 cm in Worldview-3. A  
41 number of studies on satellite imagery processing methods and applications have been  
42 conducted. A few papers providing sensor overviews have been published, including [7-9].

Blais (2004) reviewed the range sensors developed over the past two decades. The studied range sensors include single point and laser scanners, slit scanners, pattern projections and time-of-flight systems. In addition, commercial systems related to range sensors were reviewed. Melesse et al. (2007) provided a survey of remote sensing sensors for typical environmental and natural resources mapping purposes, such as urban studies, hydrological modeling, land-cover and floodplain mapping, fractional vegetation cover and impervious surface area mapping, surface energy flux and micro-topography correlation, remotely sensed-based rainfall and potential evapotranspiration for estimating crop water requirement satisfaction indexes. Recently, a survey on remote sensing platforms and sensors was provided by Toth & Józków (2016). The authors gave a general review in current remote sensing platforms, including satellites, airborne platforms, UAVs, ground-based mobile and static platforms, sensor georeferencing and supporting navigation infrastructure, and provided a short summary of imaging sensors.

In the literature, we found that overviews of remote sensing sensors were quite rare. One reason for this finding was that this topic is fairly broad. Usually, one can find detailed knowledge from thick books or a very simple overview from some webpages. As most readers need to obtain relevant knowledge within a reasonable time period and with a modest depth, the contribution of our paper is valuable. In this paper, we review the history of remote sensing, the interaction of the electromagnetic spectrum and objects, imaging sensors and non-imaging sensors (e.g., laser rangefinders/altimeters), and commonly used satellites and their characteristics. In addition, future trends and potential applications are addressed. Although this paper is mainly about satellite sensors, there is no apparent boundary between satellite sensors and airborne, UAV-based, or ground-based sensors except that satellite sensors have more interaction with the atmosphere. Therefore, we use the term “remote sensing sensors” generally.

## **2. Remarkable development in space-borne remote sensing**

Although the term ‘remote sensing’ was introduced in 1960. However, in practice, remote sensing has a long history. In the 1600s, Galileo used optical enhancements to survey celestial bodies [10]. An early exploration of prisms was conducted by Sir Isaac Newton in 1666. Newton discovered that a prism dispersed light into a spectrum of red, orange, yellow, green, blue, indigo, and violet and recombined the spectrum into white light. One hundred years later, in 1800, Sir William Herschel explored the thermal infrared electromagnetic radiation for the first time in the world. Herschel measured the temperature of light that had been split with a prism into the spectrum of visible colors. In the following decades, some attempts were made with aerial photographs using cameras attached to balloons. However, the results were not satisfactory until 1858, when Gaspar Felix Tournachon took the first aerial photograph successfully from a captive balloon from an altitude of 1200 feet over Paris. Later, in 1889 in Labruguiere, France, Arthur Batut attached a camera and an altimeter to kites for the first time so that the image scale could be determined. Therefore, he is considered to be the father of kite aerial photography. Then, at the beginning of the twentieth century, the camera was able

to be miniaturized (e.g., 70 g) so that it was easily carried by pigeons. The Bavarian Pigeon Corps took the first aerial photos using a camera attached to a pigeon in 1903. During the First World War, the use of aerial photography grew. Later, in 1936, Albert W. Stevens took the first photograph of the actual curvature of the earth from a free balloon at an altitude of 72,000 feet. The first space photograph from V-2 rockets was acquired in 1946. Table 1 addresses the evolution of the remote sensing, excluding the early development stage. The table starts with the use of aerial photographs for surveying and mapping as well for military use. The milestones in this evolution (see Table 1) reference [7] and [10]. Additionally, recent developments in microsatellites and satellite constellations are also listed in Table 1.

Table 1. Evolution and advancement in remote sensing satellites and sensors

### 3. Characteristics of materials in Electromagnetic Spectrum (EMS)

Remote sensors remotely interact with objects on the surface of the Earth. Objects on the surface of the Earth generally include terrain, buildings, road, vegetation, and water. The typical materials of these objects that interact with the EMS are categorized into groups: transparent and opaque (partly or fully absorbed).

#### 3.1. Electromagnetic Spectrum

Figure 1. The electromagnetic spectrum. Image from UC Davis ChemWiki, CC-BY-NC-SA 3.0.

Figure 1 contains the EMS range from gamma rays to radio waves. In remote sensing, typical applications include the visible light (380 nm-780 nm), infrared (780 nm-0.1 mm), and microwave (0.1 mm-1 m) ranges. This paper treats the terahertz (0.1 mm-1 mm) range as an independent spectral band separate from microwaves. Remote sensing sensors interact with objects remotely. Between sensors and the earth surface, there is atmosphere. It is estimated that only 67% of sunlight directly heats the Earth [11]. The remainder of the light is absorbed and reflected by the atmosphere. The Earth's atmosphere strongly absorbs infrared and UV radiation. In visible light, typical remote sensing applications include the blue (450-495 nm), green (495-570 nm) and red (620-750 nm) spectral bands for panchromatic or multispectral or hyperspectral imaging. Current bathymetric and ice LIDAR generally uses green light (e.g., NASA's HSRL-1 LIDAR, with a spectrum of 532 nm). However, new experiments have shown that in the blue spectrum, such as at 440 nm, the absorption coefficient for water is approximately an order of magnitude smaller than at 532 nm, and 420-460 nm light can penetrate relatively clear water and ice much deeper, offering substantial improvements in sensing through water for the same optical power output, thus reducing power requirements [11]. The red spectrum together with near infrared (NIR) is typically used for vegetation applications. For example, the Normalized Difference Vegetation Index (NDVI) is used to

1 evaluate targets that may or may not contain live green vegetation. Infrared is invisible  
2 radiant energy. Usually, infrared is divided into different regions: near IR (NIR, 0.75-1.4  $\mu\text{m}$ ),  
3 shortwave IR (SWIR, 1.4-3  $\mu\text{m}$ ), mid-IR (MIR, 3-8  $\mu\text{m}$ ), longwave IR (LWIR, 8-15  $\mu\text{m}$ ), and far  
4 IR (FIR, 15-1000  $\mu\text{m}$ ). Alternatively, according to the ISO 20473 scheme, another division is  
5 proposed as NIR (0.78-3  $\mu\text{m}$ ), MIR (3-50  $\mu\text{m}$ ) and FIR (50-1000  $\mu\text{m}$ ). Most of the infrared  
6 radiation in sunlight is in the NIR range. Most of the thermal radiation emitted by objects near  
7 room temperature is infrared [14]. In nature, on the surface of the Earth, almost all thermal  
8 radiation consists of infrared in the mid-infrared region, which is a much longer wavelength  
9 than that in sunlight. Of these natural thermal radiation processes, only lightning and natural  
10 fires are hot enough to produce much visible energy, and fires produce far more infrared than  
11 visible light energy. NIR is mainly used in medical imaging and physiological diagnostics.  
12 One typical application of MIR and FIR is thermal imaging, e.g., night vision devices. In the  
13 MIR and FIR spectrum bands, water shows high absorption, and biological systems are highly  
14 transmissive.

15 With regard to the terahertz spectrum band, terahertz frequencies are useful for investigating  
16 biological molecules. Unlike more commonly used forms of radiated energy, this range has  
17 rarely been studied, partly because no one knew how to make these frequencies bright enough  
18 [12] and because practical applications have been impeded by the fact that ambient moisture  
19 interferes with wave transmission [13]. Nevertheless, terahertz light (also called T-rays) has  
20 remarkable properties. T-rays are safe, non-ionizing electromagnetic radiation. This light  
21 poses little or no health threat and can pass through clothing, paper, cardboard, wood,  
22 masonry, plastic and ceramics. This light can also penetrate fog and clouds. THz radiation  
23 transmits through almost anything except for not metal and liquid (e.g., water). T-rays can be  
24 used to reveal explosives or other dangerous substances in packaging, corrugated cardboard,  
25 clothing, shoes, backpacks and bookbags. However, the technique cannot detect materials  
26 that might be concealed in body cavities [14].

27 The terahertz region is technically the boundary between electronics and opt-photonics [15].  
28 The wavelengths of T-rays—shorter than microwaves, longer than infrared—correspond with  
29 biomolecular vibrations. This light can provide imaging and sensing technologies not  
30 available through conventional technologies, such as microwaves [16]. For example, T-rays  
31 can penetrate fabrics. Many common materials and living tissues are semi-transparent and  
32 have ‘terahertz fingerprints’, permitting them to be imaged, identified, and analyzed [17]. In  
33 addition, terahertz radiation has the unique ability to non-destructively image physical  
34 structures and perform spectroscopic analysis without any contact with valuable and delicate  
35 paintings, manuscripts and artifacts. In addition, terahertz radiation can be utilized to  
36 measure objects that are opaque in the visible and near-infrared regions. Terahertz pulsed  
37 imaging techniques operate in much the same way as ultrasound and radar to accurately  
38 locate embedded or distant objects [18]. Current commercial terahertz instruments include  
39 Terahertz 3D medical imaging, security scanning systems and terahertz spectroscopy. The  
40 latest breakthrough research (9.2016) on terahertz applications was that MIT invented a  
41 terahertz camera that can read a closed book. This camera can distinguish ink from a blank  
42 region on paper. The article indicates that ‘In its current form the terahertz camera can

accurately calculate distance to a depth of about 20 pages [19]. It is expected that in the future, this technology can be used to explore and catalog historical documents without actually having to touch or open them and risk damage.

Regarding microwaves, shorter microwaves are typically used in remote sensing. For example, this region is used for radar, and the wavelength is just a few inches long. Microwaves are typically used for obtaining information on the atmosphere, land and ocean, such as Doppler radar, which is used in weather forecasts, and for gathering unique information on sea wind and wave direction, which are derived from frequency characteristics, including the Doppler effect, polarization, back scattering, that cannot be observed by visible and infrared sensors [20]. In addition, microwave energy can penetrate haze, light rain and snow, clouds, and smoke [21]. Microwave sensors work in any weather condition and at any time.

### 3.2. Objects and Spectrum

When light encounters an object, they can interact in several different ways: transmission, reflection, and absorption. The interaction depends on the wavelength of the light and the nature of the material of the object.

Most materials exhibit all three properties when interacting with light: partly transmission, partly reflection and partly absorption. According to the dominant optical property, we category objects into two typical types: transparent materials and opaque materials.

Transparent material allows light to pass through the material without being scattered or absorbed. Typical transparent objects include plate glass and clean water. Figure 2 shows the transmission spectrum of Soda-lime glass with a 2-mm thickness. Soda-lime glass is typically used in windows (also called flat glass) and glass containers. From Figure 2, can be seen that Soda-lime glass nearly blocks UV radiation. Nevertheless, it has high transmittance in the visible light and NIR wavelengths. It is easy to understand that when a laser scanner with a wavelength of 905 nm, 1064 nm or 1550 nm hits a flat glass window or a glassy balcony, over 80% of the laser energy passes through the glass and hits the objects behind the window. Another typical example of transmissive material is clear water. Water transmittance is very high in the blue-green part of the spectrum but diminishes rapidly in the near-infrared wavelengths (see Figure 3). Absorption, on the other hand, is notably low in the shorter visible wavelengths (less than 418 nm) but increases abruptly in the range of 418-742 nm. A laser beam with a wavelength of 532 nm (green laser) is typically applied in bathymetric measurements as this wavelength has a high water transmittance. According to the Beer-Lambert law, the relation between absorbance and transmittance is as follows: Absorbance =  $-\log(\text{Transmittance})$ .

Figure 2. Transmission spectrum of Soda-lime glass with a 2-mm thickness. Obtained from [22]

Figure 3. Liquid water absorption spectrum. Obtained from [23].

Opacity occurs because of the reflection and absorption of light waves off the surface of an object. The reflectance of light depends on the material of the surface that the light encounters. There are two types of reflection: one is specular reflection, and another is diffuse reflection. Specular reflection is when light from a single incoming direction is reflected in a single outgoing direction. Diffuse reflection is the reflection of light from a surface such that an incident ray is reflected at many angles rather than at just one angle, as in the case of specular reflection. Most objects have mixed reflective properties [24]. Representative reflective materials include metals such as aluminum, gold and silver. From Figure 4, can be seen that aluminum has a high reflectivity over various wavelengths. In the visible light and NIR wavelengths, the reflectance of aluminum reaches up to 92%, while this value increases to 98% in MIR and FIR. Silver has a higher reflectance than aluminum when the wavelength is longer than 450 nm. At a wavelength of 310 nm, the reflectance of aluminum is zero [25]. The reflectance of gold significantly increases at a wavelength of approximately 500 nm, reaching a very high reflectance starting in the infrared. This figure indicates that regardless of the wavelength at which the sensor operates, it is inevitable to encounter high reflection from aluminum surfaces.

Figure 4. Reflective spectrum of metals: aluminum, gold and silver.

The physical characteristics of the material determine what type of electromagnetic waves will and will not pass through it. Figure 5 shows examples of the reflection spectrums of dry bare soil, green vegetation and clear water. The reflection of dry bare soil increase as the wavelength increases from 400 nm to 1800 nm. Green vegetation has a high reflectance in the red light and near infrared regions. These characteristics have been applied for distinguishing green vegetation from other objects. In addition, the previous figure shows that water has a low absorbance in the visible light region. Figure 5 shows that water reflects visible light at a low rate (<5%). Indirectly, the figure indicates that water has a high transmittance in the visible light range.

Figure 5. Examples of reflective materials. Image referenced from [26].

#### 4. Spaceborne sensors

Spaceborne sensors have been developed for over 40 years. Currently, approximately 50 countries are operating remote sensing satellites [9]. There are more than 1000 remote sensing satellites available in space, and among these, approximately 593 are from the USA, over 135 are from Russia, and approximately 192 are from China [27].

Conventionally, remote sensors are divided into two groups: passive sensors and active sensors, as we described in the first section. However, as sensor technology has advanced,



nothing has been absolute. For example, an imaging camera is usually regarded as a passive sensor. However, in 2013, a new approach that integrates active and passive infrared imaging capability into a single chip was developed. This sensor enables lighter, simpler dual-mode active/passive cameras with lower power dissipation [28]. Alternatively, remote sensing sensors can be classified into imaging sensors and non-imaging sensors. In terms of their spectral characteristics, the imaging sensors include optical imaging sensors, thermal imaging sensors and radar imaging sensors. Figure 6 illustrates the category in terms of imaging sensors and non-imaging sensors.

Figure 6. Spaceborne Remote Sensing Sensors.

#### 4.1. Optical imaging sensors

Optical imaging sensors operate in the visible and reflective IR ranges. Typical optical imaging systems on space platform include panchromatic systems, multispectral systems and hyperspectral systems. In a panchromatic system, the sensor is a monospectral channel detector that is sensitive to radiation within a broad wavelength range. The image is black and white or grayscale. A multispectral sensor is a multichannel detector with a few spectral bands. Each channel is sensitive to radiation within a narrow wavelength band. The resulting image is a multilayer image that contains both the brightness and spectral (color) information of the targets being observed. A hyperspectral sensor collects and processes information from tens to hundreds of spectral bands. A hyperspectral image consists of a set of images. Each narrow spectral band forms an image. The resulting images can be utilized to recognize objects, identify materials and detect elemental components. Table 2 gives a more detailed description of these optical imaging systems. It can be seen that when a light is split into multiple spectrums, the greater the number of spectrums is, the lower the imaging resolution will be. That is, a panchromatic image usually presents a higher resolution than a multispectral/ hyperspectral image. Pan-sharpening technique was introduced by Padwick et. al in 2010 [29] for improving the quality of multispectral images. This method combines the visual information of the multispectral data with the spatial information of the panchromatic data, resulting in a higher-resolution color product equal to the panchromatic resolution.

Table 2. Satellite optical imaging systems

#### 4.2. Thermal IR imaging sensors

A thermal sensor typically operates in the electromagnetic spectrum between the mid-to-far infrared and microwave ranges, roughly between 9-14  $\mu\text{m}$ . Any object with a temperature above zero can emit infrared radiation and produce a thermal image. A warm object emits more thermal energy than a cooler object. Therefore, the object becomes more visible in an image. This is especially useful in tracking a living creature, including animals and the human body, and detecting volcanos and forest fires because a thermal image is independent from

the lights in a scene and is available whether it is daytime or nighttime. Commonly used thermal imaging sensors include IR imaging radiometers, imaging spectroradiometers and IR imaging cameras. Currently, the satellite IR sensors in use include ASTER, MODIS, ASAA and IRIS. Table 3 lists the thermal IR sensors and their applications.

Table 3. Thermal IR sensors

### 4.3. Radar imaging sensors

A radar (microwave) imaging sensor is usually an active sensor, operating in an electromagnetic spectrum range of 1 mm-1 m. The sensor transmits light to the ground, and the energy is reflected from the target to the radar antenna to produce an image at microwave wavelengths. The radar moves along a flight path, and the area illuminated by the radar, or footprint, is moved along the surface in a swath. Each pixel in the radar image represents the radar backscatter for that area on the ground. A microwave instrument can operate in cloudy or foggy weather and can also penetrate sand, water, and walls. Unlike infrared data that help us identify different minerals and vegetation types from reflected sunlight, radar only shows the difference in the surface roughness and geometry and the moisture content of the ground (the complex dielectric constant). Radar and infrared sensors are complimentary instruments and are often used together to study the same types of Earth surfaces [30]. Frequently used microwave spectrum bands for remote sensing include the X-band, C-band, S-band, L-band and P-band. Specific characteristics of each band can be found in Table 4.

Table 4. Commonly used Frequency and Spectrum bands of Radar imaging sensors

(Referenced from [31])

Conventional passive microwave imaging instruments (such as cameras or imaging radiometers) provide imagery with a relatively coarse spatial resolution when compared to an optical instrument. The diffraction-limited angular resolution of a camera aperture is directly proportional to the wavelength and inversely proportional to the aperture dimension [33]. To achieve a similar spatial resolution as optical instruments, a large antenna aperture (e.g., tens of kilometers) is needed. Clearly, it is not feasible to carry such a large antenna on a space platform. SAR is an active microwave instrument that resolves the above problem. SAR utilizes the motion of the spacecraft to emulate a large antenna from the small craft itself. The longer the antenna is, the narrower the beam is. A fine ground resolution usually results from a narrow beam width. At present, a synthesized aperture can be several orders of magnitude larger than the transmitter and receiver antenna. It has become possible to produce an SAR image with a half meter of accuracy [32].

Specifically, SAR uses microwaves to illuminate a ground target with a side-looking geometry and measures the backscatter and traveling time of the transmitted waves reflected by objects on the ground. The distance the SAR device travels over a target in the time taken for the

radar pulses to return to the antenna produces the SAR image. Typically, SAR is mounted on a moving platform, such as a spaceborne or airborne platform. According to the combination of frequency bands and polarization modes used in data acquisition, SAR can be categorized into [33]:

- Single frequency (L-band, or C-band, or X-band)
- Multiple frequency (Combination of two or more frequency bands)
- Single polarization (VV, or HH, or HV)
- Multiple polarization (Combination of two or more polarization modes)

The main parameters of designing and operating SAR include the power of electromagnetic energy, frequency, phase, polarization, incident angle, spatial resolution and swath width. There are different types of SAR techniques, including ultra-wideband SAR, terahertz SAR, differential interferometry (D-InSAR), and interferometric SAR (InSAR). Ultra-wideband SAR utilizes a very wide range of frequencies of radio waves. This method results in a better resolution and more spectral information on target reflectivity. Therefore, this approach can be applied for scanning a smaller object or a closer area. Terahertz radiation works in the spectral range from 0.3-10THz, typically between infrared and microwave. Typical characteristics of this wavelength range include its transmission through plastics, ceramics and even papers. Terahertz radiation is extraordinarily sensitive to water content. If the material has even a small amount of water content, it will be fairly absorptive to terahertz light. Therefore, this radiation can be applied in detecting lake shores or coastlines. InSAR, also called interferometric SAR, is a technique that produces measurements from two or more SAR images. This technique is widely applied in DEM production and monitoring glaciers, earthquakes, and volcanic eruptions [34]. D-InSAR requires taking at least two images with the addition of a DEM. The DEM can be acquired from GPS measurements. This method is mainly used for monitoring subsidence movements, slope stability analysis, landslides, glacier movement, and 3D ground movement [35]. Doppler radar is used to acquire a distant object's velocity relative to the radar. The main applications of this technique include aviation, sounding satellites, and meteorology. In general, SAR can reach a spatial resolution on the order of a millimeter.

#### 4.4. Non-imaging sensors

A non-imaging sensor measures a signal based on the intensity of the whole field of view, mainly as a profile recorder. In contrast with imaging sensors, this type of sensor does not record how the input varies across the field of view. In the remote sensing field, the commonly used non-imaging sensors include radiometers, altimeters, spectrometers, spectroradiometers and LIDAR. Table 5 provides detailed information about conventional non-imaging sensors. In the remote sensing field, non-imaging sensors typically work in the visible, IR, and microwave spectral bands. The applications for non-imaging sensors mainly focus on height, temperature, wind speed and other atmospheric parameter measurements.

Table 5. Non-imaging sensors

Lasers have been applied in measuring the distance and height of targets in the remote sensing field. We generally call a laser scanning system a LIDAR (light detection and ranging) system. Satellite LIDAR, Airborne LIDAR, mobile mapping LIDAR and terrestrial LIDAR are different carrier platforms. Laser sources include solid state lasers, liquid lasers, gas lasers, semiconductor lasers, and chemical lasers (see Table 6). Typical laser sources for laser rangefinders and laser altimeters include semiconductor laser and solid state lasers. Semiconductor lasers typically produce light sources at wavelengths of 400-500 nm and 850-1500 nm. Solid state lasers generate light at wavelengths of 700-820 nm, 1064 nm, and 2000 nm. Satellite or airborne LIDAR systems are typically operated at wavelengths of 905 nm, 1064 nm and 1550 nm. One of the main considerations for wavelength selection is the atmospheric transmission between the sensor and the surface of the Earth. Lower transmittance at a given wavelength means less solar radiation at that wavelength. The transmittance at 905 nm is approximately 0.6, while the wavelengths of 1064 nm and 1550 nm have similar transmittances of approximately 0.85. In addition, wavelength selection can also be a cost issue. Diode lasers at 905 nm are inexpensive compared to Nd: YAG solid state lasers at 1064 nm and diode lasers at 1550 nm. In 2007, the cost of diode lasers at 1550 nm was 2.5 times higher than lasers at 905 nm. However, the wavelength of 1550 nm is a good candidate for use in invisible wavelength eye-safe LIDAR. The higher absorption of 1550 nm light by water makes it eye safe, and this absorption is approximately 175 times greater than that of 905 nm light. In addition, the solar background level of light at 1550 nm is approximately 50% lower than that of light at 905 nm. Making measurements at 1550 nm also results in a higher signal to noise ratio compared to using a beam at 905 nm. All in all, when ignoring the cost issue, a wavelength of 1550 nm has a clear advantage over light at 905 nm [36].

In general, at a wavelength of 1064 nm, vegetation has stronger reflectance than soil, while at a wavelength of 1550 nm, soil shows greater a reflectance than vegetation. Taking measurements with different wavelengths is beneficial for object classification. Green lasers with a wavelength of 532 nm are usually pumped by a solid state laser (Nd: YAG). This type of laser is widely used for bathymetric measurement. Table 7 lists the typical applications of different laser light wavelengths.

Table 6. Typical Laser sources

Table 7. Commonly used laser wavelength

Referenced from [36]

#### 4.5. Commonly used remote sensing satellites

So far, more than 1000 remote sensing satellites have been launched. These satellites have been updated with new generation satellites. The few spectral sensors from the earliest missions have been upgraded to hyperspectral sensors with hundreds of spectral bands. The spatial and spectral resolutions have been improved on the order of one hundred fold. Revisit times have been shortened from months to daily. In addition, more and more remote sensing data are available as open data sources. Table 8 gives an overview of the commonly used remote sensing satellites and their parameters.

Table 8. Remote sensing satellites

(Referenced from [37-40])

#### 5. Future and discussions

A common expectation from the remote sensing community is the ability to acquire data at high resolutions (spatial, spectral, radiometric and temporal), at low cost, with open resource support and for the creation of new applications by the integration of spatial/aerial and ground-based sensors.

The development of smaller, cheaper satellite technologies in recent years has led many companies to explore new ways of using low Earth orbit satellites. Many companies have focused on remote imaging, for example, to gather optical or infrared imagery. In the future, a low-cost communications network between low Earth orbit satellites can be established to form a spatial remote sensing network. This network would integrate with a large number of distributed ground sensors to establish ground-space remote sensing. In addition, satellites can easily cover large swaths of territory, thereby supplementing ground-based platforms. Thus, data distribution and sharing would become very easy.

Openness and sharing resources can promote the utilization of remote sensing and maximize its output. In recent years, open remote sensing resources have made great progress. Beginning on 1 April, 2016, all Earth imagery from a widely used Japanese remote sensing instrument operating aboard NASA's Terra spacecraft since late 1999 has been available to users everywhere at no cost [41]. On 8 April, 2016, ESA announced that an amazing 40-cm resolution WorldView-2 European cities dataset would be available for download through the Lite Dissemination Server. These data are made available free of charge. This dataset was collected by ESA, in collaboration with European Space Imaging, over the most populated areas in Europe at 40-cm resolution. These data products were acquired between February 2011 and October 2013. The dataset is available to ESA member states (including Canada) and European Union Member states [42]. In open remote sensing resources, NASA (USA) was a pioneer in sharing its imagery data. NASA has been cooperating with the open source community, and many NASA projects are also open source. NASA has also set up a special website to present these projects. In addition, some commercial companies like DigiGlobal

(USA) have also partly opened their data to the public. In the future, more and more open resources will become available.

Future applications in remote sensing will combine the available resources from space/aerial/UAV platforms with ground-based data. The prerequisites of such resource integration are as follows: i) The spatial resolution of satellite data is high enough to match ground-based data; for example, both spatial data and ground data are in the same order of accuracy. WorldView-3 has achieved a 30-cm spatial resolution, which is comparable with ground-based sub-centimeter data accuracy (e.g., 2 cm in mobile laser point cloud); ii) Cloud-based calculation supports big datasets from crowd-sourced remote sensing resources. The current situation shows promising support for the integration of multiple sources of remote sensing data. We expect to see new applications developing in the coming years.

## 6. Conclusions

This paper investigated remote sensing sensor technology both broadly and in depth. First, we reviewed some fundamental knowledge about the electromagnetic spectrum and the interaction of objects and the spectrum. It helps to understand that when a sensor is operated in a certain wavelength how environmental objects will react to it. In addition, we also highlighted the terahertz region of the spectrum. Since little research has been done on this range, in the future, research efforts on new applications of terahertz radiation may be worth exploring. On the interaction of sensors with the environment, typical examples in glass, metal, water, soil and vegetation were provided. Remote sensors were presented in terms of imaging sensors and non-imaging sensors. Optical imaging sensors and thermal imaging sensors, radar imaging sensors and laser scanning were highlighted. In addition, commonly used remote sensing satellites, especially those from NASA and ESA, were detailed in terms of launched time, sensors, swath width, spectrum bands, revisit time and spatial resolution.

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